### Development and Validation of a Multidisciplinary Spacesuit Model

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# Outline

- Why a Spacesuit?
- Model Description
- Subsystem Details
- Model Validation
- Optimization Preview
- Conclusion
- Acknowledgment

### Spacesuits 101

- Why do we need a spacesuit?
  - Regulate temperature
  - Provide oxygen for breathing
  - Pressurized environment
- Important issues to consider
  - Mobility
  - Mass
  - Stowage Volume
  - Pre-breathe time



#### Model Overview

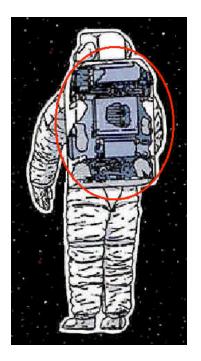
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Spacesuit Garment
Mobility

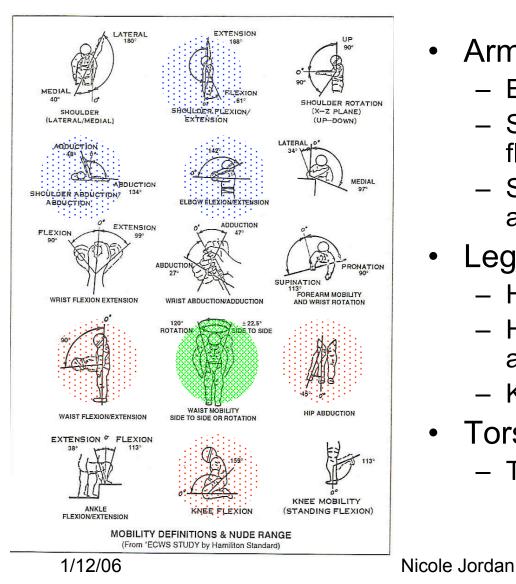


- Primary Life Support System (PLSS)
  - O2 Flow
  - Thermal Regulation

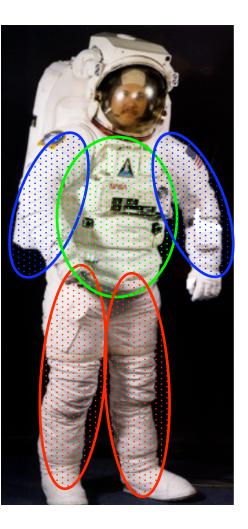
– Power



## **Mobility Subsystem**



- Arms
  - Elbow flexion
  - Shoulder flex/ex
  - Shoulder ad/abduction
- Legs
  - Hip flexion
  - Hip ad/abduction
  - Knee flexion
- Torso •
  - Torso rotation

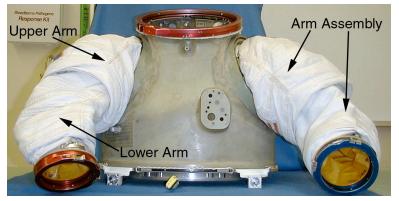


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# Mobility Subsystem

- Mobility = f(Range of Motion, Torque)
- Empirical and Physical Model

0	All Soft Suit		
0.3	HUT, Soft Legs, Soft Arms (EMU)		
0.5	HUT, Soft Legs, Hard Arms		
0.8	HUT, Hard Legs, Soft Arms		
1	All Hard Suit (AX-5)		

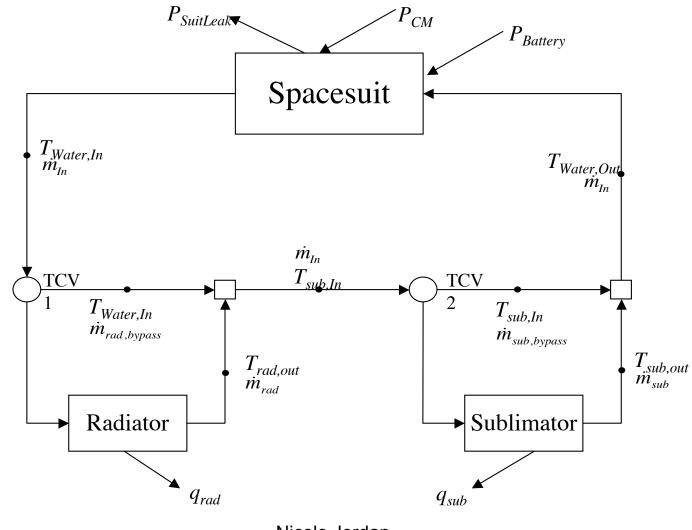






 $mobility = w_{arms} \left(-\sum ROM_{arms} + \sum Torque_{arms}\right) + w_{legs} \left(-\sum ROM_{legs} + \sum Torque_{legs}\right) + w_{torso} \left(-\sum ROM_{torso} + \sum Torque_{torso}\right)$ 

#### **Thermal Subsystem**



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### Power Subsystem

- Given battery energy density, battery volumetric density, and power needs of suit, model calculates mass and volume of power subsystem
- Technology options modeled: NiCd Batteries, NiH<sub>2</sub> Batteries, Regenerative Fuel Cells, NiMH Batteries, Lithium-Ion Batteries, AgZn Batteries, Li-Solid Polymer, Electrolyte, Li-Solid Polymer, Inorganic Electrolyte
- Mass calculation includes supporting hardware:

$$m_{PMAD} = 0.02 * P_{demand} + 0.025 * P_{demand}$$

# Oxygen Subsystem

- Models oxygen ventilation loop
- Primary determinant of backpack geometry
- CO<sub>2</sub> technologies modeled:
  - LiOH (single use)
  - Metox (multi-EVA use)

### Model Validation

- Validated at the system and subsystem level
- Integrated model validated against the Extravehicular Mobility Unit (EMU) currently used on the ISS

Output	EMU	Model	% Error
Overall Mass (kg)	53.69	53.72	0.06%
Pre-Breathe Time (hr)	4	4.67	16.75%
02 Tank Volume	0.0079	0.0073	7.59%
Sublimator Water (kg)	3	2.9	3.33%
Battery Mass (kg)	6.81	6.67	2.06%

#### **Model Interactions**

S/O	Mass	Volume	PBT	Mobility
Oxygen	+	+	++	++
Thermal	+	+	-	-
Structures	++	++	++	++
Power	+	+	_	-

- indicates no correlation
- + indicates slight correlation
- ++ indicates strong correlation

## Multi-Objective Optimization

- Four-Objective Optimization using an *N*-Branch Tournament Genetic Algorithm (GA)
- 4 Design Variables
  - $[x_1, x_2, x_3, x_4]$  = [Pressure, Hardness, Power Technology,CO<sub>2</sub> Removal Technology]
- 4 Objectives
  - Minimize(Mass)
  - Minimize(Stowage Volume)
  - Minimize(Pre-breathe Time)
  - Maximize(Mobility) → Minimize(Mobility Metric)
- Hyper-Space Diagonal Counting (HSDC) Visualization Method

## Conclusions

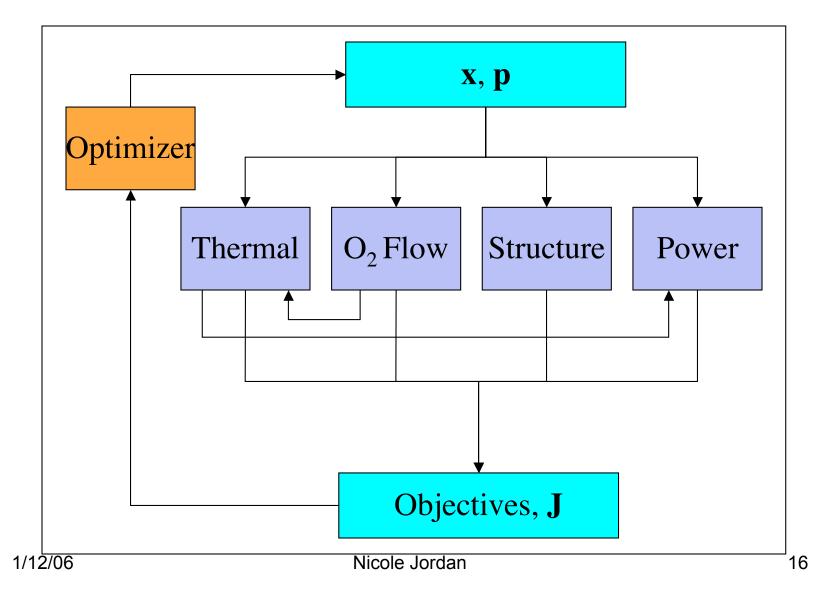
- First attempt at a multidisciplinary spacesuit model
- Has potential to be a very valuable tool in the design of future spacesuits
- Need to increase the fidelity of model
- In the future, we will use the model to investigate commonalities between Mars, Moon, and micro-gravity spacesuits

### Acknowledgment

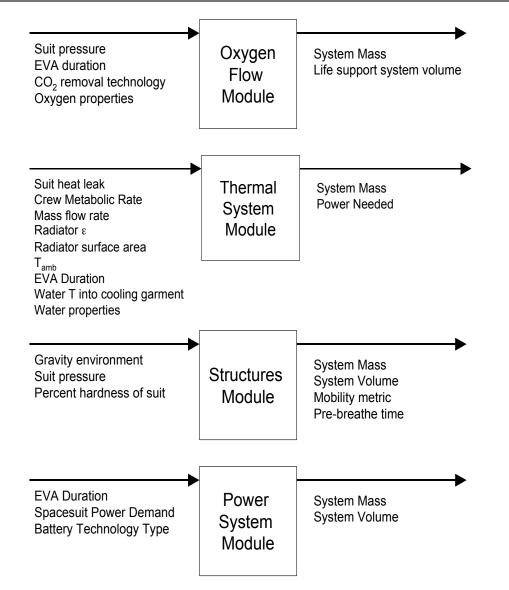
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#### **Back-up Slides**

#### **Model Description**



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